

Forest Machine Hybridization

Subjects: [Energy & Fuels](#)

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Global climate change is currently taking place, and the change is associated with strong weather fluctuations, which result in calamities, whether of biotic or abiotic origin. During these calamities, there is a glut of wood in the market, and thus its price falls. The falling price requires a reduction in the costs associated with its harvesting. Deployment of hybrid machines can present a solution for this issue and hybrid machines have lower fuel consumption, which contributes to the total costs by up to 82% . The solution correlates with the global trend of reducing emission limits for working machines. The Stage V emission standard is currently valid in the EU.

Hybrid drives of forest machines (harvester, forwarder, and skidder) are based on solutions that come from the automotive industry. From the sector of machine hybridization, Sellgren mentioned so-called “engine downsizing”, when engine sizes are scaled down and emissions are thus reduced. The most common hybrid drive design currently utilizes electricity with an aim to solve the issue of a lack of the required power of a smaller engine, for example in harvesters. Such hybridization is referred to in the literature as the electro-hybrid drive.

hybrid drive

forestry machine

electro-hybrid

hydraulic hybrid

electro-hydraulic hybrid

1. Electro-Hybrids

The electro-hybrid drive includes a generator, an inverter, an electrical storage device, and an electric motor ([Figure 1](#)). The generator generates electrical energy, which is led into the inverter, a type of static converter [\[1\]\[2\]](#). The static converter is a power electronic device without any moving parts, which converts parameters of electrical energy of one type (instantaneous value and time course of voltage and current, frequency, and number of phases) to other parameters of the required electrical energy of another type [\[2\]](#).

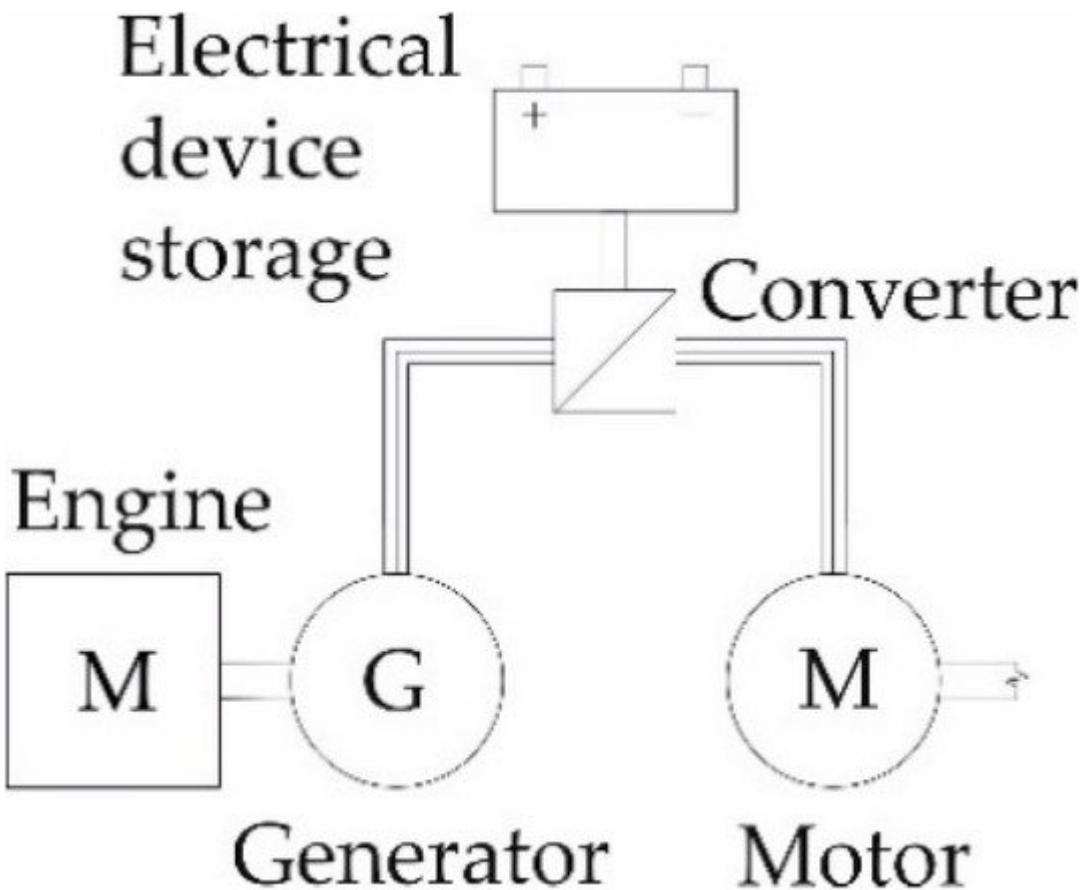


Figure 1. Electro-hybrid configuration.

The inverter converts the input DC voltage to the output AC voltage [3]. Ishida and Higurashi [4] mentioned in their research the use of a DC converter which, as Kús [3] stated, modifies the DC voltage and current parameters. Procházka et al. [5] showed the use of a static converter, which a DC converter and an inverter. The reason for using the word inverter instead of static converter is their identical names in the English language, but the difference in electrical engineering is quite obvious thanks to Kús [3].

Batteries, capacitors, or supercapacitors can be considered electrical storage devices. Batteries must at first be charged with electrical energy, which is converted into chemical energy during charging [6]. When discharging, the opposite is true, i.e., chemical energy is converted into electrical energy. The capacitor is composed of two conductive (metal) electrodes, with the dielectric between them [7]. When charged, the capacitor interrupts the DC circuit due to a non-conductive dielectric [6]. The supercapacitor is a capacitor with larger physical dimensions and a higher capacity [8]. The supercapacitor has a higher energy density than the battery and a shorter charging (and discharging) time, in the order of seconds compared to the battery, where the charging time lasts several hours [9]. Some solutions combine these types of electrical storage devices [10]. The energy, stored in such a way, is led through the static converter into the electric motor, which converts electrical energy into mechanical energy [5]. The electric motor can even become, at the same time, a generator, i.e., recuperation [11]. The recuperating motor supplies active power to the network and takes reactive power from the network for magnetization [2].

Depending on the location of the electro-hybrid assembly in the drive system, the series configuration, parallel configuration, power split configuration, or series configuration with fuel cells (Figure 2) can be recognized. Due to the high consumption of logging machines, the series configuration with fuel cells cannot be used [11]. Therefore, parallel and series configurations are the most suitable for use in these machines.

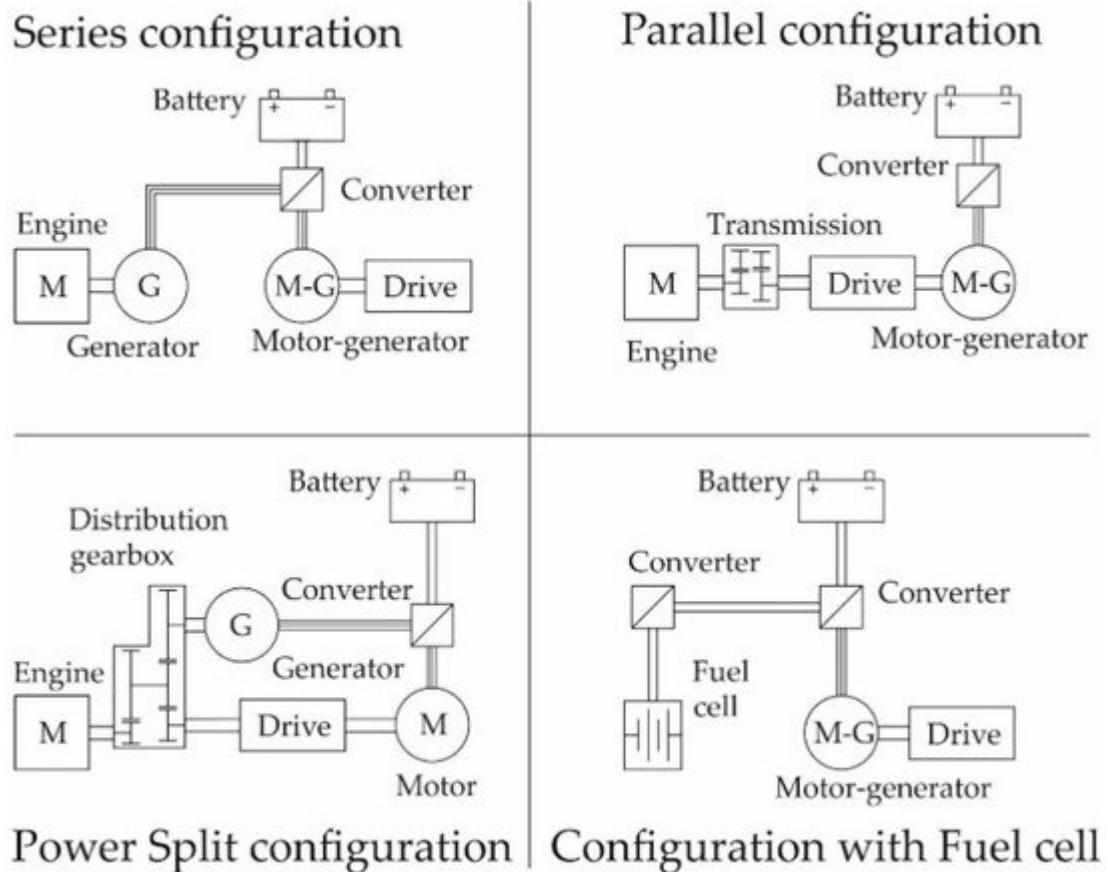


Figure 2. Types of electro-hybrid drive arrangement.

The system from the manufacturer Logset Oy is the first available electro-hybrid harvester for the forestry market. It is a parallel hybrid configuration that utilizes an electric motor connected to the shaft of an internal combustion engine which is also the generator [12]. Switching of the electric motor between the motor and the generator mode is realized by the control unit. The control unit has the task of sensing the load of the internal combustion engine and, in case of any excessive load, starting the electric motor, thus relieving the load on the internal combustion engine [13]. When the engine load is below the normal limit, the electric motor acts as a generator, charging the supercapacitors [12]. The supercapacitors can be discharged and recharged within 9 to 10 s [13]. In comparison with the same conventional diesel harvester, the Logset hybrid system is 72% more powerful, with a 54% increase in torque, and hydraulic flow is increased by up to 27% [14].

Procházka et al. [5] also used a battery in their research of a hybrid harvester drive. The system uses a synchronous motor with permanent magnets which is able to work in generator mode [5]. Currently, a prototype hybrid harvester from Agama a.s. is being researched in cooperation with the Faculty of Forestry and Wood

Technology of Mendel University in Brno. A similar system, however, not specified in detail, was created by the manufacturer Elforest Technologies AB, the product of which is known as "Elturbo". The manufacturer, together with Pro Silva Qyj, created, for example, the hybrid harvester 910 EH, which included Elturbo. The battery was used to store the electric energy [15]. An interesting solution was created by the manufacturer Koller GmbH with the KX 800 E excavator yarder. The manufacturer again used an electric motor with a generator mode and connected them to the winches. In the case when an external force acted on the winches, recuperation took place. The energy obtained was stored in the supercapacitors [16]. The energy obtained was used again under high load conditions of the internal combustion engine of the machine, the same as the C860 hybrid wood chipper from Kesla Oyj. It is important to add that all the hybrid systems mentioned used parallel configurations.

The hybrid excavator system of Komatsu Ltd. is another interesting design with a combined arrangement (Figure 3). The system works with one supercapacitor and two electric motors, which are also generators [10]. The first electric motor is located between the internal combustion engine and the pump on the shaft. The electric motor primarily generates electricity and also relieves the internal combustion engine when it is overloaded. A second electric motor is used instead of a swinging hydraulic motor, while preserving the function. When braking, it recuperates which reduces, with respect to the properties of the supercapacitor, the possibility of electricity becoming unavailable in the electrical storage device [10]. A similar system has been created for an experimental excavator by CNH Industrial, known by its New Holland Agriculture brand, but with the use of a battery.

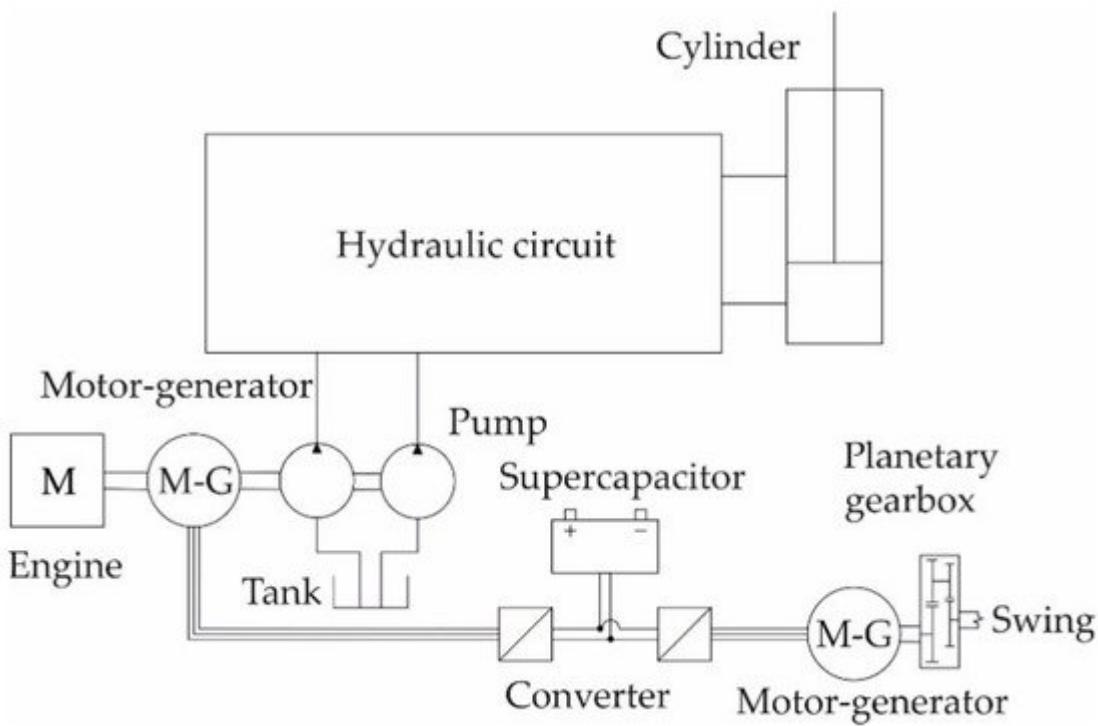


Figure 3. Hybrid system of Komatsu Ltd.

The system from Hitachi Ltd., utilizing a system similar to that of the excavator of Komatsu Ltd., is another hybrid solution that can be used in CTL technology. However, they have chosen the battery as their electrical storage device and added a generator for recharging the battery with respect to its charging time [10]. The generator is

driven by a hydraulic motor which is located in the drilled branch (T) of the hydraulic circuit, which leads into the tank. The same design for generating electricity for recharging the electrical storage device is also used by the motor-generator energy regeneration system (MGERS). Lin and Wang [17] stated that a hydraulic motor without the possibility of flow control, which a generator is connected to, is mounted on the return branch of the hydraulic circuit. Electricity is led by the inverter (converter) into the storage device and then back to the electric motor, which is connected to the output shaft of the internal combustion engine upstream of the hydraulic motor. The system uses a supercapacitor as the electrical storage device [18].

A different method of electro-hybridization, which uses the same components by replacing one part of a conventional drive, is worth mentioning, in particular, replacement of the whole hydrostatic section and one part of the mechanical section of the hydrostatic-mechanical drive of the harvesters, forwarders, and excavators. A forwarder from the company Elforest Technologies AB, where each wheel is equipped with an electric motor, can serve as an example. Stoddart [19] stated that these are 30 kW AC electric motors. The generator connected to the distribution gearbox is the source of electricity. If the machine goes downhill, there is the possibility of recuperation. The battery was chosen as the electrical storage device. Thanks to the described design, the total weight of the machine was decreased [20]. The testing of the machine is finished but data are not available. Rong-Feng et al. [21] mentioned that electric motors can be fitted one by one to the bogie axle. Electric motors for wheel drive also use Agama a.s. technology in their hybrid trailers. An electric motor with the possibility of generator mode was placed in one wheel on each side. It was then connected to a converter and a lithium battery. Further, an electric motor driven by a hydraulic motor was connected to the converter. The solution from Agama a.s. allowed energy recuperation during trailer braking [22]. All these mentioned solutions used the series configuration. The same system as that of Agama a.s. and Elforest AB is used by Kesla Oyj in the hybrid wood chipper Kesla C 860 H. A Kesla uses a supercapacitor for energy storage [23].

As far as excavators are concerned, one part of the drive in the mechanical section has been replaced; there is a generator downstream of the internal combustion engine, which generates electricity through the converter into the supercapacitor and the battery. The supercapacitor covers the power peaks of the internal combustion engine, and if the battery is charged adequately, the machine is able to operate without the engine running. From the electrical storage device, electricity is led to the converters/inverters in our case, thanks to which it is clear that electricity will be led to AC electric motors. The electric motors are connected to the pumps, followed by conventional hydraulic circuits, while the lifting hydraulic motor and the hydraulic motor of the swing have separate circuits. Such a solution enables recuperation of the electric motors when the upper part of the machine is rotated and the boom is lowered [10].

2. Hydraulic Hybrids

The method of hybridization uses a hydrostatic pressure system. A hydraulic accumulator is used in all available designs. Bansal [24] showed a pressure tank, in which the incompressible hydraulic fluid is kept under pressure from an external source. Pressure energy of the liquid is converted in the accumulator into the deformation energy of the compressed gas, which is then converted back to the pressure energy at the appropriate moment [25].

Gangwar et al. [26] add that the accumulator allows the hydraulic system to cope with extreme pressure requirements through a less powerful hydraulic pump and also to respond more quickly to a temporary demand. The use of a hydraulic accumulator also smooths the flow pulses caused by the hydraulic pump. Heikkilä [27] stated that hydro-pneumatic accumulators are more advantageous than electrical storage devices thanks to their simplicity and cost-effective design.

Some methods of solutions also use a hydraulic motor with the possibility of hydraulic fluid flow control, which can also work as a hydraulic pump (hereinafter referred to as a motor–generator) [28]. Pivoňka [29] stated that this possibility is offered, for example, by axial piston pumps. In case of low-pressure energy consumption in the operating cycle the motor–generator supplies excess energy into the hydraulic accumulator, and in case of high energy consumption, it can be used for the motor mode depending on the layout of the hydraulic accumulator in the circuit [1].

Hydraulic hybrids can be broken down into series (Figure 4) and parallel (Figure 5) ones according to their arrangement [30]. Hippalgaonkar and Ivantysynova [31] present a series–parallel configuration. The configuration can be called a power split as it is in principle mixed wiring in electro-hybrids. In the case of a series connection, all the mechanical energy is transformed into hydraulic energy and then converted back into mechanical energy. On the other hand, the parallel connection converts mechanical energy into hydraulic energy only in case of a low load of the internal combustion engine and converts it into mechanical energy when the internal combustion engine is loaded heavily to relieve the load [30]. The series–parallel configuration, i.e., the power split configuration, uses both systems and can be seen in Figure 6.

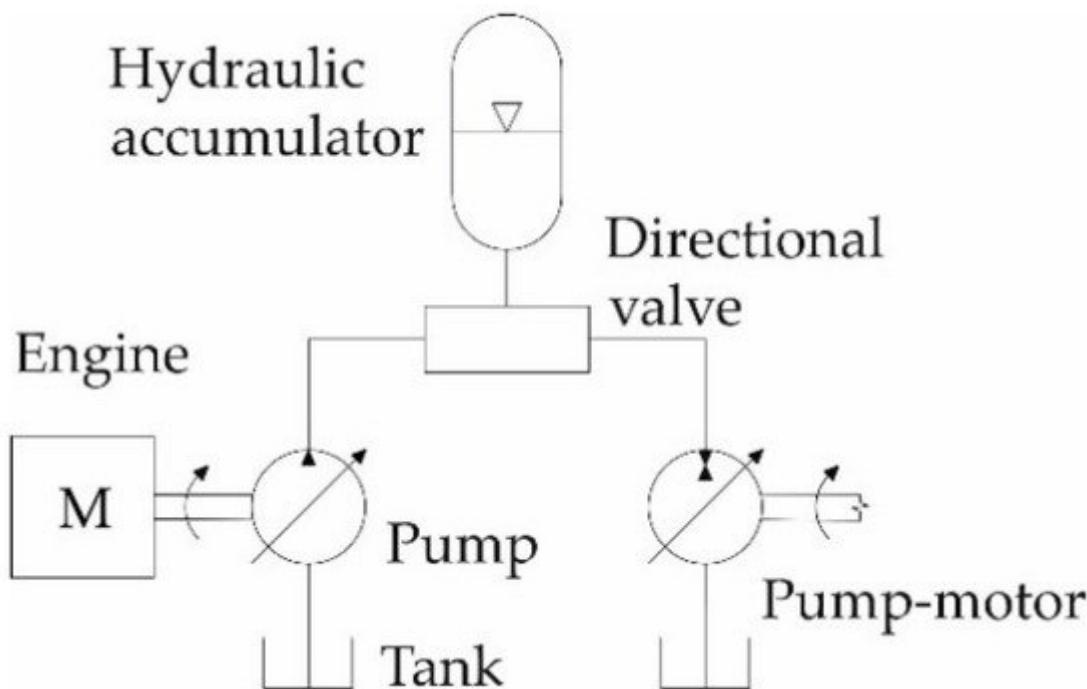


Figure 4. Series configuration.

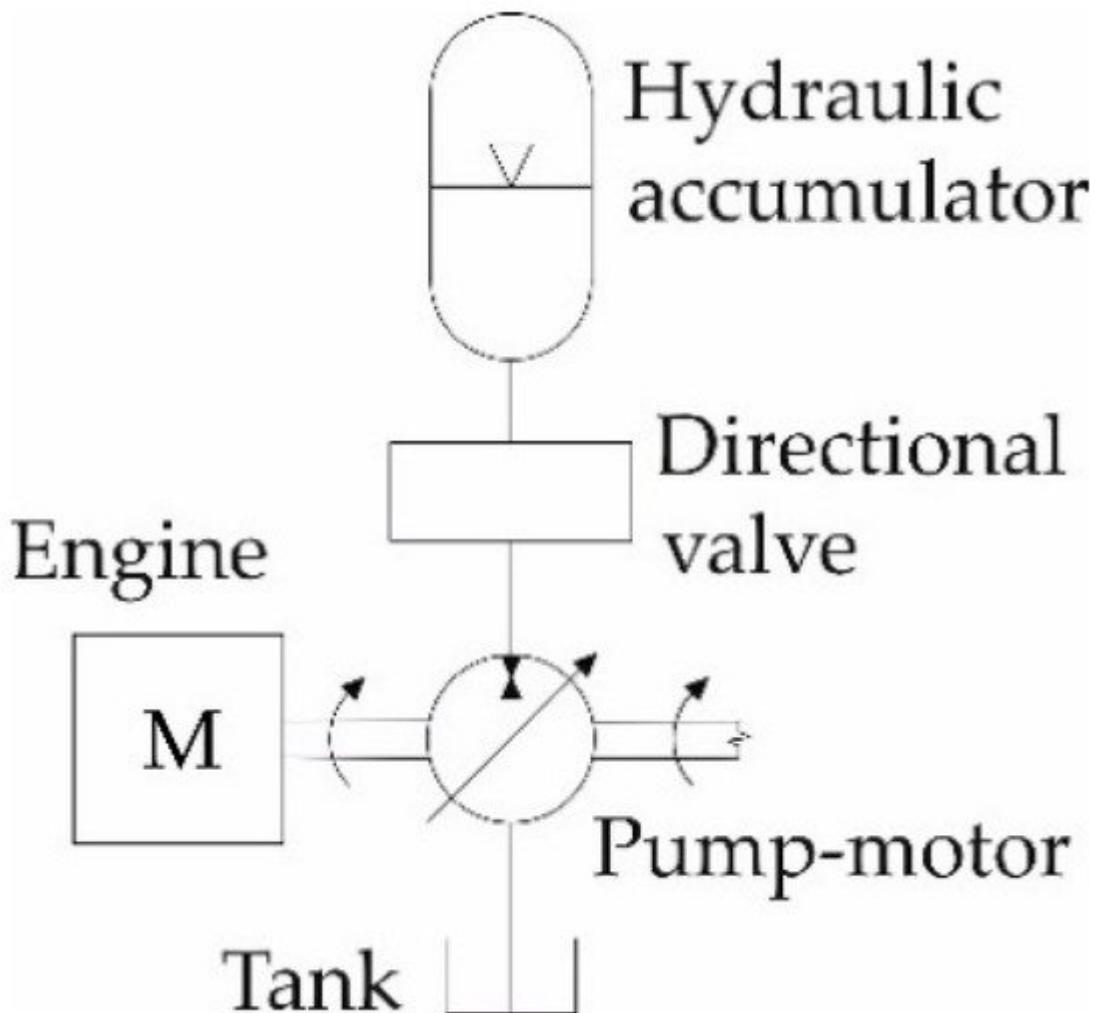


Figure 5. Parallel configuration.

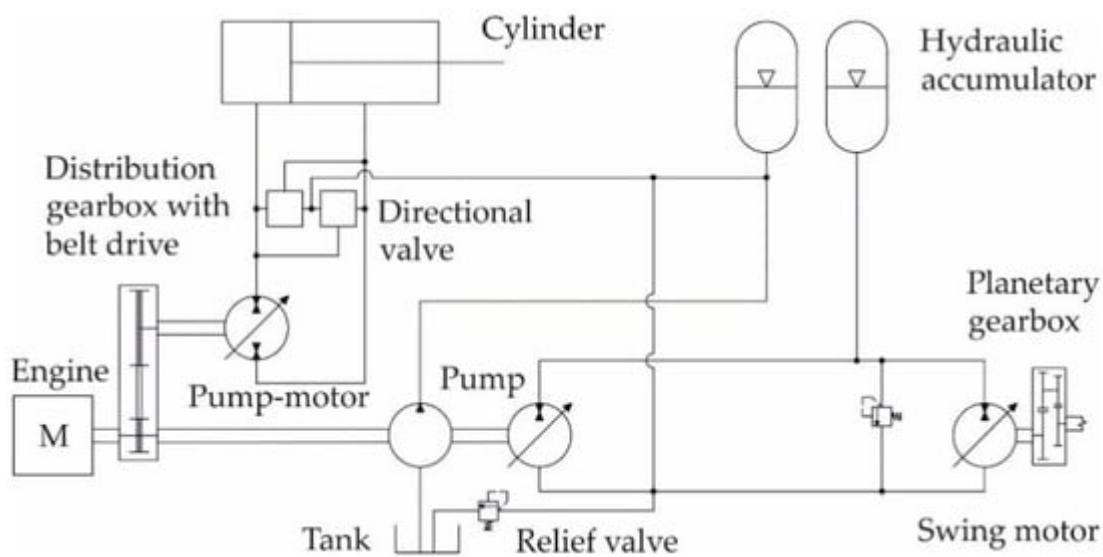


Figure 6. Power split (series-parallel) configuration.

The simplest systems do not currently use such types of hydraulic motor. They use only the accumulator itself, which is connected to the existing open-loop hydraulic circuit. The accumulator is connected by a two-way proportional valve (to the system under pressure), which is connected with the already mentioned circuit, where a hydraulic servo-valve can also be found, which is located on the line upstream from the hydraulic motor [28]. However, a connection from the tank with the pipeline ending under the surface also leads into the servo-valve.

Hydraulic oil is supplied into such systems under pressure by a one-way pump with the possibility of flow control. In case of excess pressure in the system, the accumulator is recharged, which then supplies the necessary pressure into the system in case of a lack of necessity [1]. Linjama et al. [28] called the machines equipped with these types of solutions hybrids without a two-way hydraulic motor with traditional valves. Amrhein and Neumann [32] stated that the system can be modified by moving the accumulator to the suction side of the hydraulic pump, while replacing it with another one that is suitable for a closed-loop hydraulic circuit. The solution enables energy recuperation from the cylinder of the hydraulic crane arm during its lowering.

Linjama et al. [28] showed motor–generator hybrids with logic valves as another method of solution. Their method is similar to the system mentioned above, but upstream of the hydraulic motors there is a system of proportional valves (Figure 7), both the one-way and the two-way types. The two-way proportional valves are located upstream of the entry to the hydraulic motor and are connected to the same section of the hydraulic circuit with one-way valves, which are connected to their own tanks, where their direction of the given fluid flow also leads. The system then does not need the hydraulic servo-valve [28].

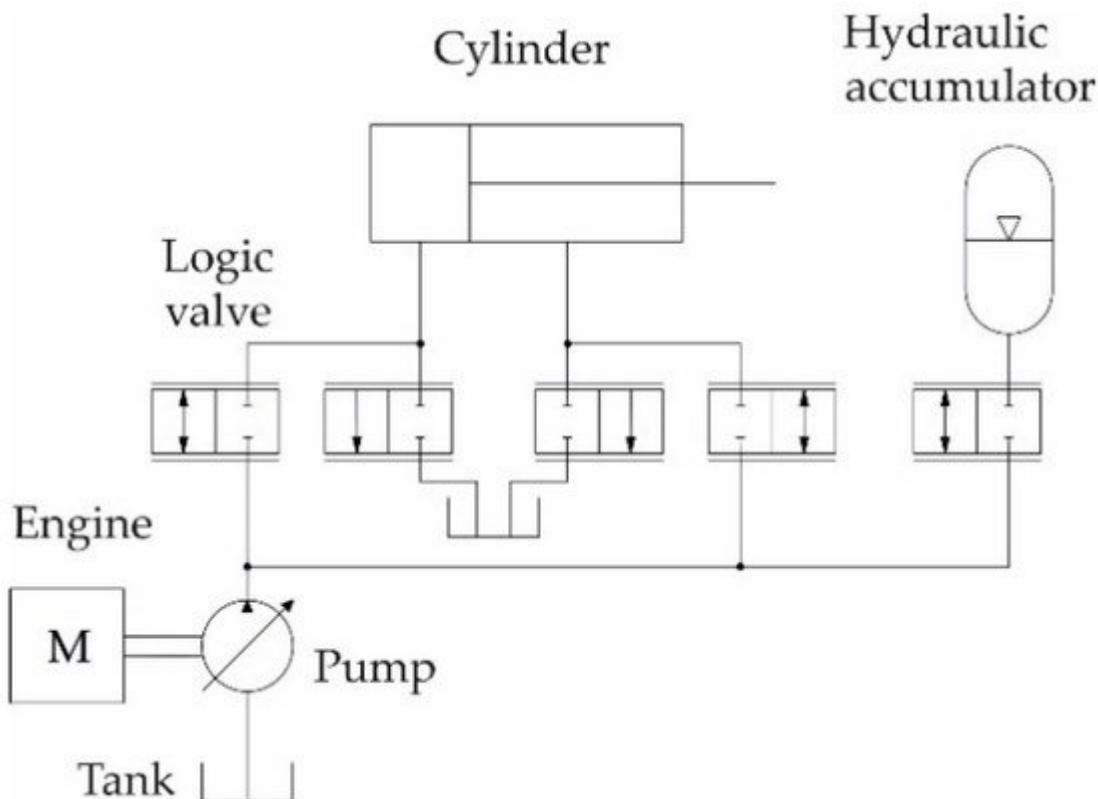


Figure 7. Hybrid without pump–motor with logic valves.

In addition to the accumulator, other types of hydraulic hybrids also utilize the already mentioned motor–generator. It is located on the shaft downstream from the primary one-way pump, which supplies pressure to the working hydraulic circuit [1]. The motor–generator itself has its own circuit, a closed-loop circuit [30]. An accumulator is connected in this circuit, upstream of which the electromagnetically controlled check valve is located [1]. Erkkilä et al. [30] mentioned the use of a controlled shut-off valve (Figure 8).

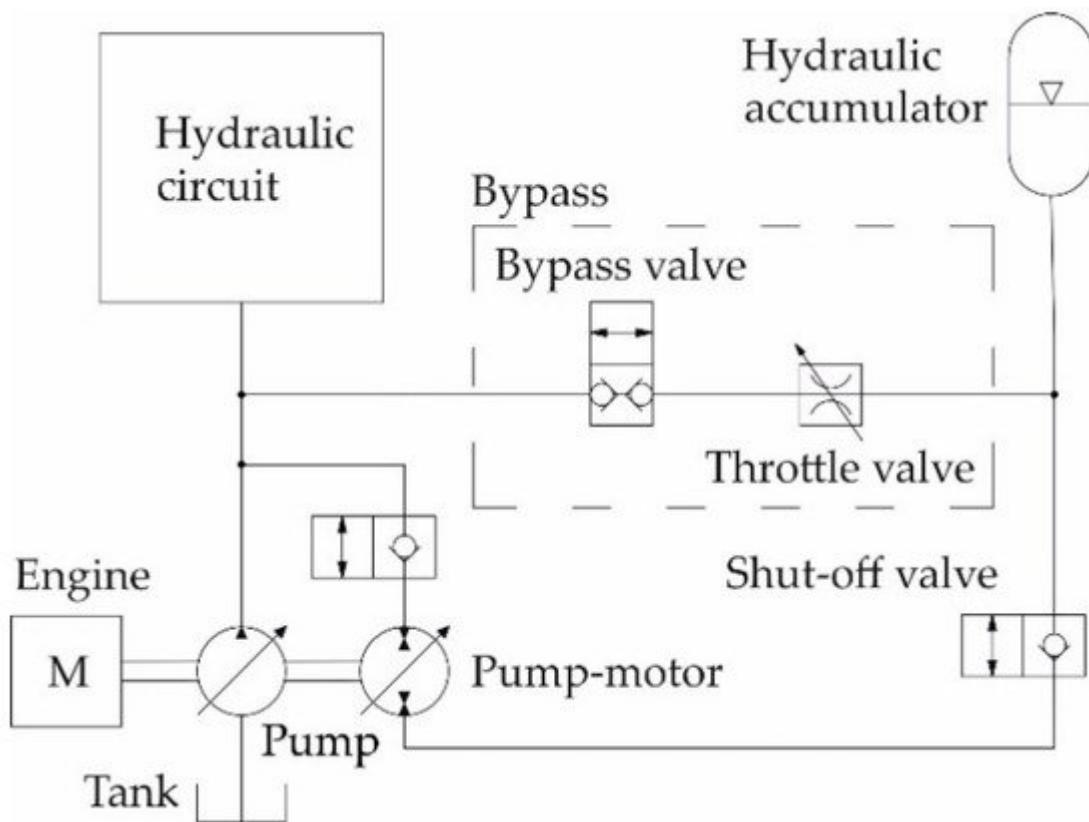


Figure 8. Hybrid solution with pump–motor.

The hydraulic circuit of the motor–generator is then connected to the primary circuit with the one-way pump. Upstream of the point of connection, as stated by Einola [1], the directional valve is used, from which two branches have their outlets, where the first branch is led into the primary circuit and the second one into the hydraulic oil tank. A different method of connection is mentioned by Erkkilä et al. [30] and also by Eniola and Kivi [33] who, instead of a switchboard, again use the same two-way valve with the possibility of fluid flow control in one direction (as for the accumulator), from which the line is then connected to the primary circuit. Machines designed in that way can be called hybrids with an extra pump–motor. The benefit of the described approach is that the flow rates of the pump–motors are summed and the installed displacement does not necessarily increase [28].

The hydraulic flywheel (HFW) drive concept, developed by Bosch Rexroth AG, is able to store the kinetic energy as well as surplus energy in situations when the combustion engine is loaded only partly [34]. The energy storage takes place with help of a battery and a motor–generator which, as mentioned in the text above, can work in the engine and generator modes. At a full load of the combustion engine, the stored hydraulic energy is converted back

to mechanical energy, which is led to the shaft coming out of the engine and its load is thus relieved. The advantage of this approach is that it can be installed in parallel with the existing system [28].

The two-pressure system (STEAM) is another solution for hybrid hydraulic drives. The STEAM system has two supply pressures, which are implemented by accumulators and a filling rotary hydraulic pump with the possibility of liquid flow control [35]. There are currently two variants of the solution. The difference between them is the absence of a hydraulic directional servo-valve upstream of the cylinder and the replacement of the logic valves by two-way proportional valves. [Figure 9](#) presents the variant with a servo-valve and logic valves. The system presented significantly reduces fuel consumption [28].

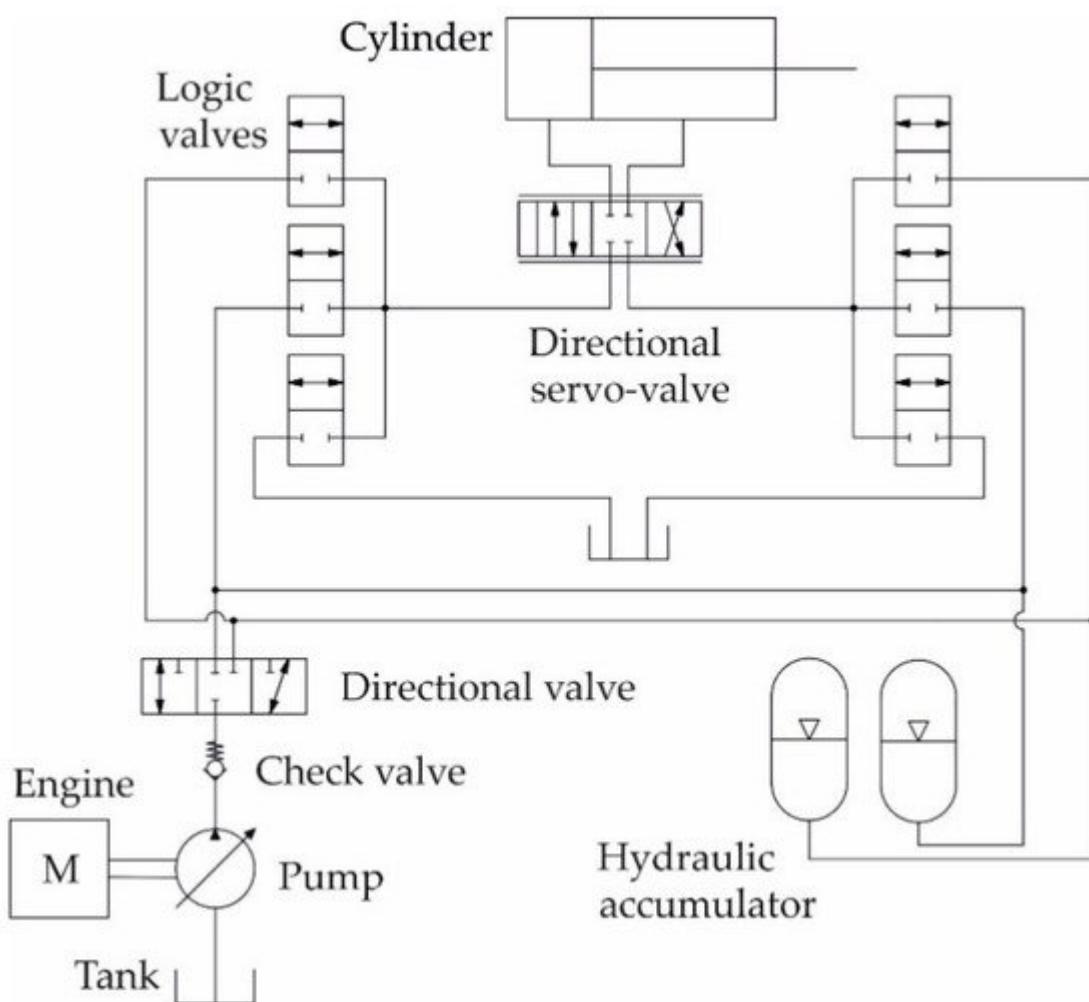


Figure 9. STEAM system with a servo-valve and logic valves.

The multi-pressure system is the last system utilized in hydraulic hybrids. The multi-pressure system uses a large number of accumulators, but the pressure energy is supplied to them with the help of one hydraulic pump only. It is, in particular, a one-way pump with an inability of fluid flow control. Linjama et al. [28] stated that it is a complex system from the point of the arrangement of all one-way or two-way logic valves. It is the most energy efficient solution of all alternatives to the hydraulic hybrids mentioned above [36]. A complete diagram of the system can be seen in [Figure 10](#).

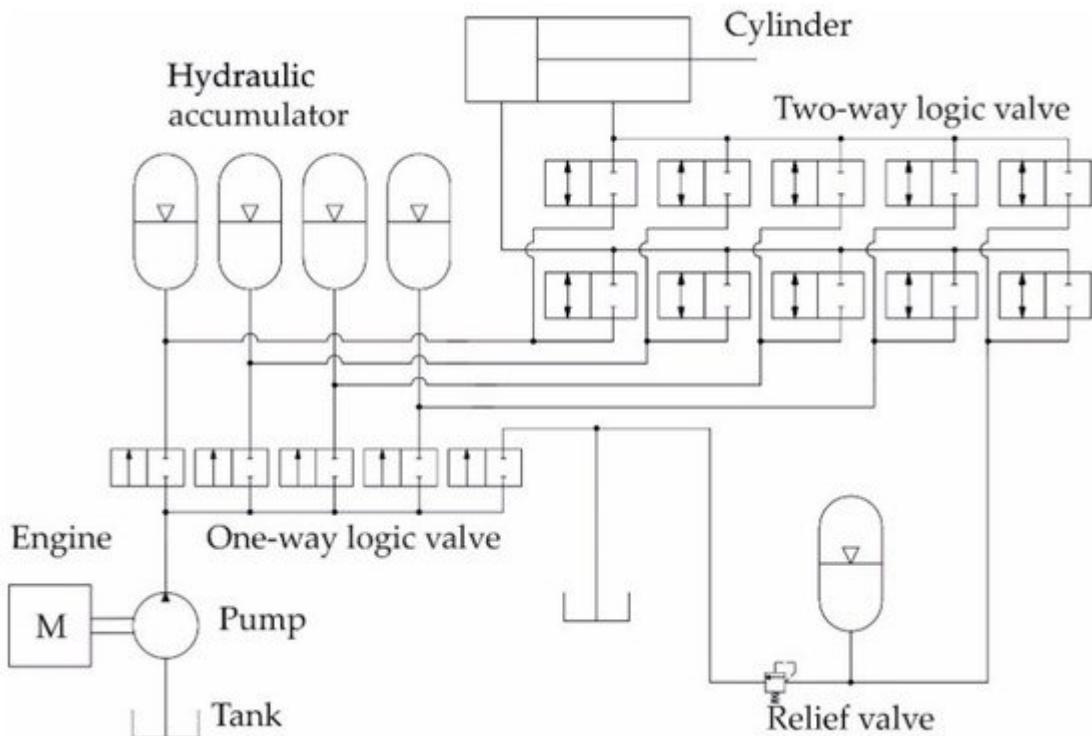


Figure 10. Multi-pressure system.

There were several machines made with a hydraulic hybrid solution to the present situation but they all were based only on the series configuration. One of them was the forwarder Caribou S 10 made by Ponsse Plc. The hydraulic hybrid was used to test two different systems of hybridization and conventional drive. Specifically, a hybrid solution without a pump–motor with logic valves and a multi-pressure system was used. In both systems, the hydraulic accumulator was connected to the hydraulic circuit of the crane, which allowed the use of a smaller pump. The volume was decreased from 130 cm^3 to 71 cm^3 [28]. A similar system, however, not specified in great detail, was created in the FORWARDER2020 concept. In the system, energy was recuperated from the lifting cylinder and from clamping the load to the grapple [37]. However, each source of recovered energy had its own battery. In this category of hybrids are included not only forwarders but also harvesters. For example, wheel harvester HSM 405H2 from Hohenloher Spezial-Maschinenbau GmbH & Co. KG (HSM forest), in which the hydraulic accumulator is connected to the hydraulic circuit of the crane and is capable of being fully charged within 4 s [38]. The hydraulic hybrid system uses a series configuration. Ponsse Plc also created a hydraulic hybrid harvester using the model Ergo with a parallel configuration. The concept was to use a pump–motor. In a situation when the pressure in the hydraulic system drops or in the case of a high load of the internal combustion engine, pressure energy from the hydraulic accumulator is released to the pump–motor. Research showed that the pump–motor had problems with the reaction dynamics and therefore the accumulator was also connected to the hydraulic circuit so it could immediately replenish the required pressure [33]. Such an adjustment was called a bypass (Figure 8).

3. Electro-Hydraulic Hybrids

At present, the hybrid drives can be broken down, based on the used energy, into the electro-hybrids and the hydraulic hybrids but we can also encounter their combination, i.e., the electro-hydraulic hybrids. The accumulator–hydraulic motor–generator energy regeneration system (AMGERS), mentioned by Lin and Wang (2012) [17], is a typical example. The system works on the same principle as the motor–generator energy regeneration system (MGERS) electro-hybrid. The AMGERS solution differs mainly by the hydraulic accumulator used. It is located between the hydraulic proportional directional valve and the tank. The hydraulic motor is located on the branch (T) leading to the tank and driving the electric generator, with the switchboards and the one-way logic valve located upstream and downstream from it (Figure 11). The electro-hybrid part is the same as in the MGERS system [18]. In the future, however, it may be a solution for forestry machinery.

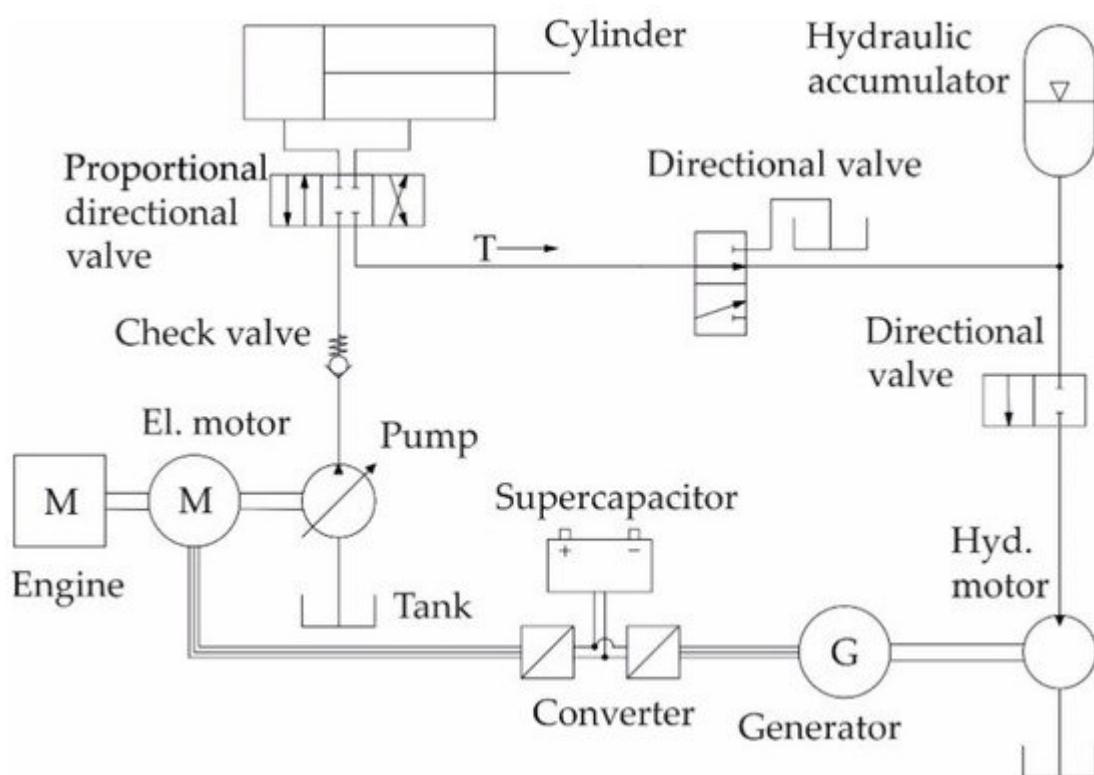


Figure 11. AMGERS.

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