

Driver Drowsiness Detection

Subjects: [Computer Science](#), [Artificial Intelligence](#) | [Others](#)

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Drowsy driving is a widespread cause of traffic accidents, especially on highways. It has become an essential task to seek an understanding of the situation in order to be able to take immediate remedial actions to detect driver drowsiness and enhance road safety.

CNN model VGG model drowsiness detection

1. Introduction

Drowsiness, defined as a feeling of sleepiness, may lead to the following symptoms: reduced response time, an intermittent lack of awareness, or the presence of microsleeps (blinks lasting more than 500 milliseconds). A lack of sleep affects thousands of drivers who drive on highways daily, including taxi drivers, truck drivers, and people traveling long distances. Moreover, the feeling of drowsiness reduces drivers' degree of attention, resulting in hazardous conditions. This significantly increases the possibility of drivers missing road signs or exits, drifting into other lanes, or even becoming involved in accidents and is one of the major contributing factors to accidents on the road. Globally, fatalities and injuries have increased yearly due to driver drowsiness while driving. Nowadays, artificial intelligence (AI) has become a significant factor in resolving many global issues. An instance of this is in the reduction in the number of accidents on the road that are caused by drowsiness via safety driver drowsiness detection technology that can help prevent accidents caused by drivers who fall asleep while driving. A multitude of behavioral and overall health issues, including impaired driving performance, have been related to sleep disturbances. Thousands of accidents worldwide are caused by insufficient sleep, exhaustion, inadequate road conditions, and weariness [1]. The public health administration is concerned about the potential involvement of inadequate driving, asleep-in-traffic accidents, deaths, and injuries that have been increasing because of such issues. **Table 1** shows the ratio of accidents and percentage of fatalities and injuries attributable to drowsy driving in the Kingdom of Saudi Arabia [2], the United Kingdom [3], the United States [4], and Pakistan [5].

Table 1. Ratio of accidents and percentage of fatalities and injuries attributable to drowsy driving.

Country	% of Accidents	% of Fatalities and Injuries
Kingdom of Saudi Arabia	11.6%	6.2%
United Kingdom	2–4%	10–20%
United States	1–3%	41%

Country	% of Accidents	% of Fatalities and Injuries
Pakistan	19%	35.5%

2. Driver Drowsiness Detection References

The study in [6] proposed to detect driver drowsiness based on eye state. A dataset was created with 2850 images separated into different classes. A novel framework based on deep learning is developed to identify driver fatigue while driving a car. The Viola–Jones face detection method is utilized to recognize the eye area, a stacked deep convolution neural network is created to determine important frames in camera sequences, and the SoftMax layer in a CNN classifier is used to classify if the driver is sleeping or non-sleeping. As a result, the model achieved an accuracy of 96%. Similarly, another study [7] proposed a video-based model using ensemble CNN (ECNN), which is comprised of four different CNN architectures to measure the degree of sleepiness. The authors used the YawDD dataset, which consists of 107 images, and a 93% F1-score was achieved using the proposed ECNN. The authors aim to investigate a more balanced and larger dataset in the future for improvement. The authors of [9] used recurrent neural networks (RNNs) and CNNs to detect drowsiness as well as a fuzzy logic-based approach to extract numerical data from the images. It was carried out using The UT-Austin Real-Life Drowsiness Dataset (UTARLDD), which includes 60 videos. RNN and CNN achieved 65%, whereas fuzzy logic obtained 33%.

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- [23], the authors aimed to create a system that can determine a driver's level of weariness using a series of images

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- The proposed system has significant potential for improving road safety and could also have applications in sleep medicine. The authors compared their approach with state-of-the-art methods and found it outperformed them in terms of accuracy, robustness, and efficiency. However, the only limitation is that a private dataset was used. Overall, this study represents an important step toward the development of reliable and accurate driver drowsiness detection systems.

A study by Alhaddad et al. [30] proposed an image-processing-based system for detecting driver drowsiness using EAR and blinking analysis. The study used a private dataset and achieved a detection accuracy of 92.10%. The system used the Dlib library for facial landmark detection and EAR calculation to detect the driver's drowsiness. The study's contribution lies in its ability to accurately detect drowsiness regardless of the size of the eye, demonstrating the effectiveness of image-processing methods for drivers' drowsiness detection. Guede-Fernández et al. [31] aimed to develop a novel algorithm for monitoring a driver's state of alertness by analyzing respiratory signals. The researchers used a quality signal classification algorithm and a Nested LOSOCV algorithm for model selection and assessment. The novel algorithm, called TEDD, was validated using a private dataset, achieving an accuracy of 96.6%. The techniques include signal processing, feature extraction, and machine learning. The results suggest that respiratory signal analysis can be an effective approach for drowsiness detection in drivers.

Vishesh et al. [32] developed a computer vision-based system to detect driver drowsiness in real time using eye blink detection. The authors used a CNN and OpenCV for image processing and feature extraction, along with a new method called horizontal and vertical gradient features (HVGFs) to improve accuracy. The study used an eye blink dataset consisting of eye images from 22 participants. CNN was trained on 80% of the dataset and tested on the remaining 20%, achieving an accuracy of 92.86% in detecting eye blinks. However, based on the experimental outcome, the proposed method can achieve an accuracy of 97%. The relationship between the rate of eye movement and the level of driver drowsiness was also analyzed. The authors found a correlation between the rate of eye movement and the degree of drowsiness, which could help detect and prevent accidents caused by driver fatigue. The study concluded that the proposed system could effectively detect driver drowsiness and be integrated with existing driver assistance systems to improve road safety. The developed prototype serves as a base for further development and potential implementation in vehicles to reduce the risk of accidents caused by drowsy driving.

Mehta et al. [33] developed a real-time driver drowsiness detection system using non-intrusive methods based on EAR and eye closure ratio (ECR). The system uses a webcam to capture images of the driver's face and extracts features from the eyes using EAR and ECR. The study used a dataset comprised facial images of 10 subjects recorded while driving. The authors manually annotated the images to indicate whether the driver was drowsy or not. The dataset was split into a training set (80%) and a testing set (20%). Moreover, the authors used a random forest (RF) to classify the drowsy and non-drowsy states of the driver based on the EAR and ECR features. The proposed model achieved an accuracy of 84% in detecting driver drowsiness. Finally, the study concluded that the proposed system could be used as a part of a driver monitoring system to improve road safety. However, the system's performance can be further improved using a larger dataset and robust classification algorithms.

Another study [34] aimed to classify drowsy and non-drowsy driver states based on respiration rate detection using a non-invasive, non-touch, impulsive radio ultra-wideband (IR-UWB) radar. A dataset was acquired, consisting of age, label (drowsy/non-drowsy), and respiration per minute. Different machine learning models were used in the study, namely, SVM, decision tree, logistic regression, gradient boosting machine (GBM), extra tree classifier, and multilayer perceptron (MLP). As a result, SVM achieved the best accuracy of 87%. A study conducted by the authors of [35] aimed to develop a system to reduce accidents caused by the driver's drowsiness. The dataset was

developed and generated by the authors. In this study, images are preprocessed using the Haar cascade classifiers to methodically improve the CNN model's hyperparameters. The performance of the model is measured using a variety of metrics, including accuracy, precision, recall, F1-score, and confusion matrix. Therefore, the model classified the input data with 97.98% accuracy, 98.06% precision, 97.903% recall, and 97.981% F1-score.