Friction Spot Stir Welding

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In the last decade, the friction stir welding of polymers has been increasingly investigated by the means of more and more sophisticated approaches. Since the early studies, which were aimed at proving the feasibility of the process for polymers and identifying suitable processing windows, great improvements have been achieved. This owes to the increasing care of academic researchers and industrial demands. These improvements have their roots in the promising results from pioneer studies; however, they are also the fruits of the adoption of more comprehensive approaches and the multidisciplinary analyses of results. The introduction of instrumented machines has enabled the online measurement of processing loads and temperature, and critical understanding of the principal aspects affecting the material flow and welds quality. Such improvements are also clearly demonstrated by the increase of the strength of recent joints (up to 99% of joining efficiency) as compared to those reached in early researches (almost 47%). This article provides a comprehensive review of the recent progresses on the process fundamentals, quality assessment and the influence of process parameters on the mechanical behavior. In addition, emphasis is given to new developments and future perspectives.

Keywords: polymers, joining, friction stir welding

1. Description of the Main Phases

Friction stir welding can be performed to produce continuous and spot welds. In this latter case, the process is called friction spot stir welding (FSSW). During FSSW, the tool simply plunges the sheets placed in lap configuration upon a certain amount of material around the tool stir leading to the formation of the bond. Friction spot stir welding can be ideally subdivided into four phases, namely: plunging, dwell, cooling and punch retraction. During the plunging phase, the tool, which rotates at a prescribed speed, is plunged against the upper sheet and the probe tip reaches the lower sheet. The material moved by the tool probe extrudes vertically in form of ejected material. If the prescribed depth is reached, dwell starts and the plunge motion is stopped, while the tool continues to rotate. This phase is aimed at heating the material surrounding the tool probe where the connection between the sheets is formed. At the end of the dwell, cooling starts. This phase consists into stopping even the tool rotation. This enables the materials to cool down. This phase can be performed by holding the vertical position of tool, or under load control. This second way was demonstrated to have the capability to close the porosities and cavities that commonly form at the interface at the stirred region and surrounding material ^[1]. This can lead to superior mechanical behaviors of the welds. As the material has sufficiently cooled down, the tool is retracted. However, if this is performed prematurely, the retraction can lead to a tearing out effect of the material surrounding the tool ^[2], or even to material attached to the tool ^[3], as shown in Figure 1. A schematic of the material surrounding the tool ^[2].



Figure 1. Main phases of FSSW development: (a) plunging; (b) dwell; (c) cooling and (d) tool retraction.

2. Material Flow

Compared to metals, polymers are characterized by much lower thermal diffusivity and higher temperature sensitivity. This promotes the development of steep thermal gradients, which in turn determine regions with great differences in terms of mechanical behavior. Consequently, after a first contact between the tool and the upper layer, a thermo-mechanical affected zone immediately develops in the region underlying the tool probe, as shown in Figure 2b.



Figure 2. Material flow during FSSW of transparent polymers: (**a**) initial position; (**b**) formation of chips; (**c**) formation of TMAZ under the tool pin; (**d**) enlargement of the TAMZ; (**e**) deep plunging and (**f**) material after dwell.

The material underlying the tool probe (TMAZ in Figure 2b,c) is characterized by a much higher temperature compared to the surrounding and underlying regions. Thus, it rapidly starts to reflow (reverse extrusion) vertically, as shown in Figure 2c. The TMAZ region extends progressively as the process proceeds, as the longer interaction time. This region also undergoes a drastic morphological change from a "U-shape" to "V-shape" as the tool shoulder approaches the upper surface of the upper sheet, as shown in Figure 2d. This owes to the contact of the tool shoulder with the polymer that leads to higher frictional heat and higher amount of material flow. The change to the "V-shape" of the TMAZ produces a dramatic increase of the mechanical behavior of the welds as it involves an increase in the extension of the weld area. Similarly, further plunging of the tool enables a downward shift of the TMAZ, which contributes to enlarge the weld area. During the dwell phase, the prolonged interaction time, which determines an increase of the frictional heat, also contributes to enlarge the welded region. This owes to heat diffusion effects that tend to increase the temperature of surrounding regions. The following cooling phase occurs. This is mainly aimed at enabling the tool retraction as soon as the material has restored its mechanical properties with a temperature well below the melting and softening temperatures of the polymer. Then, the tool is retracted. This comes with the formation of a blind hole in the joint (weld nugget) that is left by the tool probe.

As a result, the geometry of the friction spot stir welds can be characterized by the weld nugget, the stirred zone and the material reflow. This last feature is generally removed by common machining operations such as milling or drilling. On the other hand, the geometry and dimension of the weld nugget and stirred material determine the mechanical behavior of the welds. The characteristic dimensions of friction spot stir welds are reported in Figure 3.



Figure 3. Effect of plunging depth on geometry of the weld ^[4].

3. Morphology of the Welds and Quality Assessment

To better comprehend the influence of the process parameters on the mechanical behavior of the welds, a deep analysis of the morphology of the joints and its influence on the failure mechanisms is required.

Figure 4a schematized an FSS weld as the connection of three regions: the upper sheet, the lower sheet and the stirred region. Although the upper and lower sheets are characterized by thermo-mechanical affected characteristics, they show their original compactness. On the one hand, the stirred region is often characterized by a certain porosity. This is mainly due to air trapped within the material during the process, as well as moisture of the original material in case of highly hygroscopic materials ^[5]. On the other hand, at the boundary of the stirred region with both the upper and lower sheets, bubbles and porosities can be highly concentrated. This is due to the thermal shrinkage of the material during the cooling phase. Steep temperature gradients develop between the stirred region and surrounding areas owing to the low thermal diffusion of polymers. Thus, the stirred region is at much higher temperature; consequently, during the cooling phase, the stirred region shrinks more than the upper and the lower sheets. This may cause the formation of a porous interface between the stirred region and the surrounding areas, as shown in Figure 4.



Figure 4. Characteristic interface areas of friction stir spot welds [74]: (a) stirred zone; (b) Aweld; (c) Aup and (d) Alow.



Figure 5. Presence of porous region at the interfaces between the stirred region and upper and lower sheets 4.

The failure of the FSS welds may occur in different ways, namely:

• Brittle fracture in the upper sheet (M1);

- Brittle fracture in the lower sheet (M2);
- Separation of the SZ from the lower sheet (M3);
- Separation of the SZ from the upper sheet (M4);
- Shear fracture in the SZ (M5).

The fracture M1 and M2 developed almost instantly as the peak load was reached. These joints are usually characterized by low absorbed energy but also high strength. Here the fracture develops almost instantly as a critical value of the stress (that is lower than the strength of the base material) is reached. The occurrence of the fracture owes to the presence of the porosities and the residual stress developing during the cooling phase and the high-temperature gradients. The brittle behavior of such failure is evident from the fracture surfaces reported in Figure 6. On the other hand, because of the above-mentioned porous interface that may originate between the stirred region and surrounding material, failure M3 and M4 may develop. In these welds, the presence of the porosities reduces the contact area, acts as a stress raiser, and induce the premature failure of the welds, as shown in Figure 7a–d. The welds characterized by a small stirred zone and especially a thin neck in correspondence of the separation line between the sheets, generally fail by shear failure, as depicted in Figure 7e–f. Here, the shear force concentrates in a small region.



Figure 6. Fracture surfaces characterized by brittle failure ^[4]: (a) upper sheet and (b) lower sheet.

Separation of Stirred Zone (SZ) from the substrate



Figure 7. Typical failure modes of friction stir spot welds ^[4]. Separation of the SZ from the substrate in (**a**) lower sheet and (**b**) upper sheet. Ductile fracture in the upper sheet (**c**) side view and (**d**) upper view. (**e**, **f**) shear fracture in the stirred zone.

The occurrence of one or another failure mode, is due to different physical phenomena, as well as the morphology and geometrical aspects. The formation of voids and porous interlayer between the stirred region and the base materials is often caused by Mode M3 or M4 failures. In addition, the presence of such defects within the stirred region may drive to shear failure (M5). However, geometrical aspects also play a great influence.

Lambiase et al. ^[1] analyzed the characteristic load-bearing areas of friction spot stir welds, to better understand the influence of the optimal plunging depth. In failure modes M3 and M4, the stirred region behaves as an almost rigid body that progressively separates from the lower and upper sheets, respectively. The fracture originates at the boundary of the stirred region and propagates along the border with the base material. Thus, welds characterized by a large interface area between the stirred region and the upper sheet A_{up} (depicted in Figure 4c) and a low value of the interface area between the SR and the bottom sheet A_{low} (depicted in Figure 4d) are prone to fail by separation with the bottom sheet. Similarly, welds characterized by a small area A_{weld} (shown in Figure 4b) are generally failed by shear failure (M5). The quality of FSS welds and particularly the mechanical behavior depends on the material stirring quality as well as the presence of process induces defects. These defects can be thus classified in:

- Geometrical: incorrect choice of the plunging depth and/or tool dimension, the shape of the tool probe;
- Morphological: formation of porosities, cavities. These depend on the selection of process parameters such as processing speed, length of the dwell time, waiting time, load/displacement control, etc.
- Residual stress: thermal shrinkage leading to residual stress and formation of voids and cavities.

4. Effect of Process Parameters

The morphology of the welds is determined by several process parameters, which can be classified into processing speeds, phases length, and geometrical aspects, as summarized in Figure 8, and Table 1.



Figure 8. Factors influencing the quality of the welds.

Table 1. Classification of process parameters for FSSW.

Category	Process Parameter	Brief Description	References
Processing Speeds	Plunge Rate	Speed of the tool during the plunging phase upon reaching the penetration depth	<u>[6][2][5][7][8]</u> [49,75,78–80]
	Rotation speed	Speed of the tool during the plunging and dwell phases	[6][7][9][10][11] [49,79,81–83]
Phases Length	Pre-heating time	Period of material pre-heating by slight plunging of the tool over the upper sheet	[6][7][9][10][11]
	Dwell time	time elapsing since the tool has reached the final penetration depth and start of cooling. During this period, the tool plunge is stopped while the tool continues to rotate	[2]6][5][8][10] [49,75,78,80,82]
	Cooling time	Period during which the tool is fully stopped (no plunging and rotation take place)	[6][9][10][11]
Geometry	Plunge depth	Axial displacement of the tool since the first contact with the upper sheet to the final position. This should be greater than the upper sheet thickness and lower than the sum of the sheet thicknesses	^{[1][3][4]} [74,76,77]
	Tool shoulder diameter	-	[1][3][4]
	Tool probe diameter	-	[3][4][12]
	Tool probe geometry	-	[3][4][12][13][14] [76,77,84–86]
Others	Plunge force	Force applied during the dwell phase when load-control is involved in the process	[1]

Before treating in detail the influence of the process parameters on the quality, morphology and mechanical behavior of friction spot stir welds, it must be noted that in some cases, there is not a full agreement among the results from different researches. This can be due by several causes, including adoption of different processing windows, materials, analysis methods, as well as depth of analysis. In addition, a further cause of misalignment concerning the influence of a given

process parameter on the strength (especially for FSSW of polymers) is also represented by the relatively limited number of papers that have dealt with that process parameter. This makes it even more difficult to generalize the achievements of a certain paper outside the processing window analyzed in that paper.

Figure 9 compares the ranges analyzed in different references for the plunging rate, tool rotation speed and dwell time. Obviously, a direct comparison would be inappropriate as different equipment's (e.g., tool dimensions, machine capabilities, etc.), and materials are involved in these works. Nevertheless, a graphical representation of these ranges may provide qualitative insights into the processing windows studied. Figure 9a indicates a general consistency among the ranges studied for the plunging rate, the most studied plunge rate ranged between 20 and 40 mm/min. On the other hand, two separate windows can be identified, as shown in Figure 9b, pertaining to low (up to 500–2000 RPM) and high tool rotation speeds (2000–5500 RPM). Finally, three ranges for the dwell time were identified, as shown in Figure 31c: short (up to 20 s), medium (from 20 to 60 s) and long (up to 150 s) dwell time. It is worth noting that the papers involving high ranges of tool rotation speed. Therefore, high tool rotation speed involves higher amount of frictional power is proportional to the tool rotation speed. Therefore, high tool rotation speed involves higher amount of frictional heat and consequently it demands lower dwell time to achieve the joints formation. Nevertheless, the adoption of low or high tool rotation speeds, which come with different power levels, may induce significant differences in temperature distributions. Since the low thermal diffusivity of polymers, the adoption of processing conditions involving high power are expected to produce steeper temperature gradients as those produced by processing conditions involving lower power amounts.



Figure 9. Processing windows analyzed in different papers concerning FSSW of polymers. Effect of (**a**) plunge rate; (**b**) tool rotation speed and (**c**) dwell time.

6. Plunge Rate

The results reported by Yan et al. ^[6], indicated the existence of an optimal value of the plunge rate. The authors asserted that extremely low values of this parameter may affect the strength of the welds. This was addressed to defect formation, water absorption, molecular weight reduction, or residual stress generation. On the other hand, as reported by Lambiase et al. ^[5], extremely high values of the plunge rate may be also detrimental. The adoption of low values of the plunge rate involves short interaction time, lower weld dimensions and worse stirring homogenization and material heating that resulted in lower load-bearing. This can be observed by comparing Figure 10a,b.



Figure 10. Influence of process parameters on welds morphology [78]. (a) reference condition; (b) reduction of tool rotation speed; (c) reduction of plunging speed; (d) increase of dwell time and (e) reduction of the waiting time.

7. Rotation Speed

The influence of the tool rotation speed (commonly indicated with llor n) has been investigated in several studies. The results do not fully agree about the effect of this process parameter. The results reported in ^{[5][9]} indicated a minor influence of n; on the other hand, other studies ^[10] determined the existence of an optimal value of the tool rotation speed that maximized the strength of the welds. Other studies determined a decreasing strength of the welds with the tool rotation speed ^[6]. It must be noted that the frictional heat produced by the tool is proportional to the tool rotation speed. Thus, higher values of n involve higher heating. However, because of the strong sensitivity of the mechanical behavior of the polymers by the temperature (especially close to the glass transition temperature), a non-linear relationship between the frictional heat and the tool rotation speed exists. Indeed, as the material is heated over the T_g, the flow stress and the Young modulus drop. This comes with a steep reduction of the contact pressure and consequently the frictional heat. Thus, the difference among the abovementioned studies can be addressed to multiple reasons, including:

- The adoption of different ranges;
- The adoption of different tool dimensions;
- The investigation of different materials, which are characterized by different T_g and softening/melting points;
- The temperature reached during the process.

8. Pre-Heating Time

The results reported in [75,78,80] indicated that this parameter has negligible effect on the quality of the joints. The studies indicated that, the addition of the pre-heating phase while joining polymers provides a local heating of the material. Only the material underlying the tool probe is heated, while no significant effect develops in the surrounding regions. This was due to the poor thermal diffusivity of polymers. Consequently, the dimension of the welds is not modified as well as the strength.

9. Dwell Time

This parameter contributes to determining the amount of frictional heat supplied to the weld when the plunging depth is reached. During this phase, the heat enlarges the weld dimension. Thus, longer dwell time involve larger welds and consequently, higher load-bearing, as can be observed by comparing Figure 10a,d reported in ^[5]. However, extremely high values of dwell time may come with detrimental effects. Indeed, as reported in ^[6], the adoption of extremely long dwell time may affect the strength of the welds. This was addressed to additional material extrusion and the generation of a cavity as well as molecular weight decrease due to mechanical scission of molecular chains.

10. Cooling Time

At the end of the dwell phase, the material of the stirred region is under a rubber or pasty state. Thus, sufficient cooling time is required to prevent the tear of the SR by means of the tooltip, as shown in Figure 10e and Figure 11. Because of the poor thermal diffusivity of the polymers, the cooling of the stirred region requires a certain time. This depends on the peak temperature reached during the process, the dimension of the stirred region, as well as the thermal properties of the materials involved (the glass transition temperature). During this phase, the tool exerts a double function. Indeed, it applies a certain pressure on the contact surfaces with the stirred region. In addition, it drains heat from the weld enabling a faster cooling. The above considerations would drive towards a temperature-based trigger for tool retraction. As soon as the temperature drops under a given temperature (depending on the thermal characteristic of the polymer), the tool can be immediately retracted. This would involve obvious advantages in terms of process efficiency and productivity. However, this is hindered by the difficulty to measure the temperature of the stirred region during the process.



Figure 11. (a) Tearing out effect ^[2] and (b) material attached to the tool owing to highly insufficient waiting time ^[3].

11. Plunge Depth

The plunge depth directly affects the geometry and dimension of the characteristic regions of welds made by FSSW. Increasing the penetration depth (s), the area Aup (and Lup) decreases while the welds area Aweld and Alow increase, as shown in Figure 2. As expected, low penetration depth involved low strength as the weld area was very restricted. On the other hand, extremely high values of the tool plunge depth involved a significant reduction of the Aup, which led to the separation of the SR from the upper sheet. This condition also led to extremely low values of the ultimate shear force, as shown in Figure 34. The highest shear force found under intermediate values of the penetration depth.



Figure 12. Influence of the penetration depth on the ultimate shear force (data from $\frac{[4]}{2}$).

12. Tool Shoulder and Probe Diameter

The results reported in ^[4] indicated that, the Ultimate Tensile Stress UTS of the welds increased when larger tool shoulder diameters were adopted and decreased with the tool probe diameter. This was due to the dimension of the stirred region and the characteristic areas. An increase of the tool shoulder diameter D comes with larger values of all the characteristic areas, Aup, Alow, and Aweld. On the other hand, the dimension of the tool probe affected these areas and induced the reduction of the UTS of the welds. The selection of the proper processing conditions enabled to achieve a joint strength of 88% in the case of polycarbonate.

13. Geometry of the Tool Probe

Being a thermo-mechanical process based on the stirring of the two materials, the geometry of the tool probe strongly influences the strength of the welds. Bilici and Yükler ^[14] firstly investigated the influence of the tool pin on the mechanical behavior of FSS welds. The authors compared six different geometries, namely: cylindrical (SC), tapered cylindrical (TC), threaded cylindrical (TH), square (SQ), triangular (TR) and hexagonal (HG).

The results reported in Figure 35 indicated that, the adoption of a threaded cylindrical probe enabled an increase of the ultimate shear force by 28% as compared to the welds made by a straight cylindrical shape, using the identical process parameters. This was addressed to a better material flow. The probe profile is also responsible of the weld nugget geometry and dimension after the tool retraction from the welds. Thus, this portion of the material does not provide any load-bearing capability. This idea drove further analysis concerning more exotic probe shapes. Yan et al. ^[13] investigated the adoption of a triflute tool probe to reduce the dimension of the weld nugget and reduce the amount of material ejected from the weld. This tool enabled significant increase in the welds force as the larger welds area. The authors also performed an experimental work concerning a double pin tool, which also enabled higher strength of the welds. The schematics of these probes are depicted in Figure 14.



Figure 13. Influence of the tool probe shape on the mechanical behavior of the welds (data extracted from [86]). (a) pin shapes and (b) effect of pin shape on the UTS of the joint.



Figure 14. Schematic of triflute and dual pin used for FSSW of polymers.

14. Effect of Plunging Force

Most of the papers concerning friction spot stir welding of polymers involved a displacement control during the entire welding process. This was due to a much simpler configuration of the machines adopted. However, this also involved the formation of a porous region surrounding the stirred zone. This region was characterized by the presence of large bubbles owing to moisture absorbed by the polymer, air trapped during the process as well as thermal shrinkage during the cooling phase. The presence of these bubbles dramatically affected the mechanical behavior of the welds as they reduced the load-bearing are and acted as stress raisers. The sequence of the material flow during friction spot stir welding of transparent polycarbonate is reported in Figure 37a–f, as reported in ^[1]. Here, the formation of the bubbles between the

stirred and surrounding regions is observed at the beginning of the dwell phase. During the plunging phase, the axial load exerts compressive stress that hinders the bubble formation. However, as the tool motion is stopped, the axial load drops leading to the easier formation of the bubbles.



Figure 15. Effect of load control during cooling phase ^[1]. Sequence of processing phases under (a-e) displacement control and (g-n) load control.

To overcome the presence of this porous region, Lambiase et al. ^[1] involved load control during the cooling phase, as shown in Figure 37g–n. This acted as compressive stress that enabled the closure of the porosities and cavities formed at the beginning of the dwell phase. The results reported by the authors were extremely promising; indeed, the welds made under load control reached a joint efficiency of 99%.

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